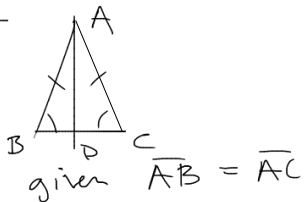


# Spherical Geometry:

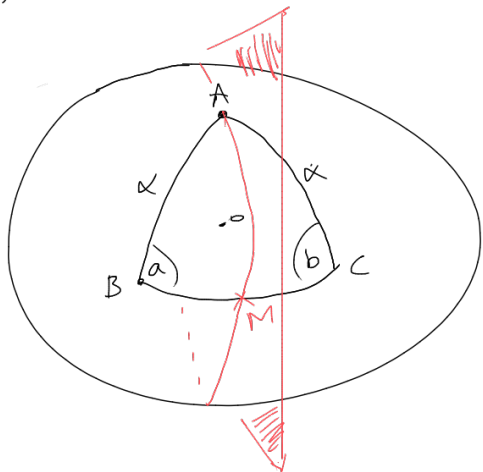
## Pons Asinorum (Isosceles triangle theorem)

Recall, in Euclidean —



proof via symmetries.  
reflection about AD is a motion, preserves angles, takes BC to CB

Similarly in Spherical



Show angle  $a = b$ .

Motions of  $S^2$  are a subset of the motions of  $\mathbb{R}^3$ .

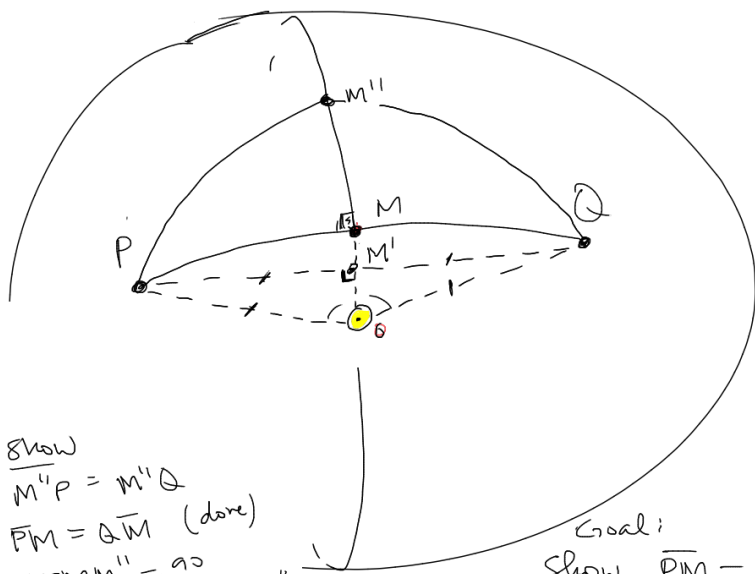
Reflection about plane containing  $\{A, O, M\}$ , w/  $M = \text{midpt of } BC$

Motions preserve angles so  $a = b$ .  
b/c this reflection takes

$$B \mapsto C$$

$$A \mapsto A$$

Given,  $P, Q \in S^2$  the set of points equidistant from both  $P, Q$  is the perp. bisector to segment  $PQ$ .



show  
 $M''P = M''Q$   
 $PM = QM$  (done)  
 $\angle PMM'' = 90 = \angle QMM''$   
 $MM'' = MM''$   
 $\text{SAS} \Rightarrow \overline{PM''} = \overline{QM''}$

Goal:  
 show  $\overline{PM} = \overline{QM}$  (spherical segments)  
 || angle b/w  $\overline{OP}$  and  $\overline{OM}$  ( $= \angle QOM'$ )  
 || angle b/w  $\overline{OP}$  and  $\overline{OM}$ . ( $= \angle POM'$ )  
 (equivalent from above)

$M = \text{midpt of } P, Q$

( $\exists$  plane  $\perp$  to  $PQ$  thru  $M$ .  
 (Euclidean 3-D geom. argument))

----- lines are inside 3-D ball

Claim:

$PM' = QM'$   
 $PO = OQ$   
 (radii)

(Plane that is the perp. bisector to  $PQ$  is the set of points whose dist to  $P$  is same as dist to  $Q$  and  $M'$  is in this plane)

$OM' = OM'$

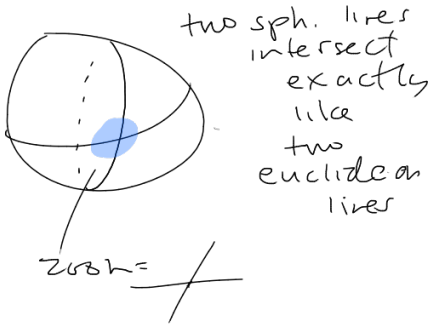
$SSS \Rightarrow \triangle OPM' \cong \triangle OQM'$

$\Rightarrow \angle POM' = \angle QOM'$

# Spherical vs. Euclidean Geometry

## Similarities

1. triangle inequality
2. two pts. determine a line
3. local intersections



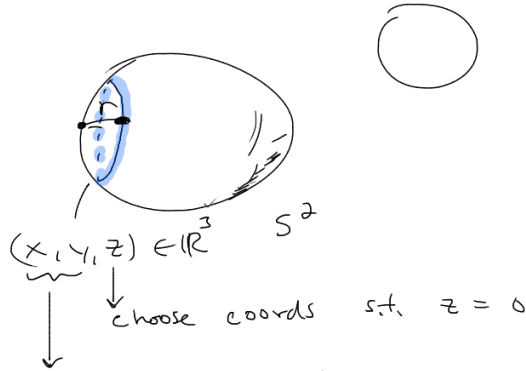
4. Distances (all things geometric) are defined by motions (preserved)
5. Homogeneity

## Differences

1. Law of Cosines / Sines
2. Formulas for Area / Circumference of Circle

$$E: A = \pi r^2 \quad | \quad E: C = 2\pi r$$

$$S_p: A = 2\pi(1 - \cos(r)) \quad | \quad S_p: C = 2\pi \sin(r)$$

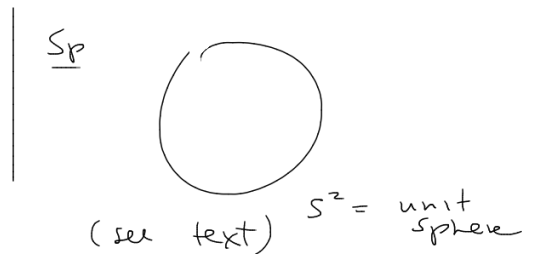


3. Bounded / Unboundedness of lengths/area
4. Triangle Angle Sum:  $(\alpha + \beta + \gamma = \pi + \text{Area } \Delta)$   
 $S_p: \alpha + \beta + \gamma > \pi$



## 5. Frames

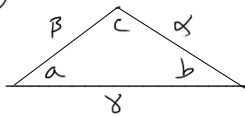
$\mathbb{E}^2$   
any 2  $\perp$  vectors determine a frame



## 6. Intrinsic Curvature

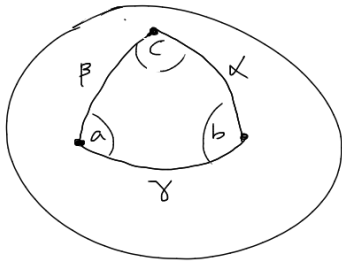
# Spherical Law of Sines: \_\_\_\_\_

Recall ( $\mathbb{E}^2$ )



$$\frac{\sin a}{\alpha} = \frac{\sin b}{\beta} = \frac{\sin c}{\gamma}$$

Similarly for  $S^2$ .

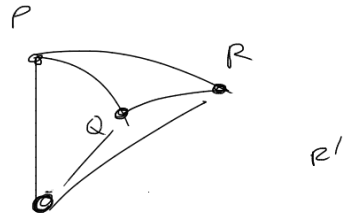


choose coordinates as before:

$$P = (0, 0, 1)$$

$$Q = (\sin \beta, 0, \cos \beta)$$

$$R = (\sin \gamma \cos \alpha, \sin \gamma \sin \alpha, \cos \gamma)$$



Idea: compute det matrix w/  $P, Q, R$  as columns.  
Recall det is invariant to change of basis.

$$\begin{vmatrix} 0 & \sin \beta & \sin \gamma \cos \alpha \\ 0 & 0 & \sin \gamma \sin \alpha \\ 1 & \cos \beta & \cos \gamma \end{vmatrix} = \begin{matrix} \sin \beta \sin \gamma \sin \alpha \\ \sin \beta \sin \gamma \cos \alpha \\ \sin \gamma \sin \alpha \cos \gamma \end{matrix}$$

Now choose different basis

Repeat

So, the 3 different bases are  $\downarrow$

$$Q = (\sin \beta, 0, \cos \beta)$$

$$R = (\sin \gamma \cos \alpha, \sin \gamma \sin \alpha, \cos \gamma)$$

$$Q = (\sin \alpha, 0, \cos \alpha)$$

$$R = (\sin \beta \cos c, \sin \beta \sin c, \cos \beta)$$

$$Q = (\sin \gamma, 0, \cos \gamma)$$

$$R = (\sin \alpha \cos b, \sin \alpha \sin b, \cos \alpha)$$